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1 **Entrainment in a dense current flowing down a rough sloping bottom in a**  
2 **rotating fluid**

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## ABSTRACT

12 Dense oceanic overflows descend over the rough topography of the conti-  
13 nental slope entraining and mixing with surrounding waters. The associated  
14 dilution dictates the fate of these currents and thus is of fundamental impor-  
15 tance to the formation of deep water masses. The entrainment in a dense  
16 current flowing down a sloping bottom in a rotating homogeneous fluid is in-  
17 vestigated using laboratory experiments, focusing on the influence of the bot-  
18 tom roughness on the flow dynamics. The roughness is idealized by an array  
19 of vertical rigid cylinders and both their spacing and height are varied, as well  
20 as the inclination of the sloping bottom. The presence of the roughness is gen-  
21 erally observed to decelerate the dense current, with a consequent reduction  
22 of the Froude number, when compared to the smooth bottom configuration.  
23 However, the dilution of the dense current due to mixing with the ambient  
24 fluid is enhanced by the roughness elements, especially for low Froude num-  
25 bers. When the entrainment due to shear instability at the interface between  
26 the dense current and the ambient fluid is low, the additional turbulence and  
27 mixing arising at the bottom of the dense current due to the roughness ele-  
28 ments strongly affects the dilution of the current. Finally, a strong dependence  
29 of the entrainment parameter on the Reynolds number is observed.

## 30 **1. Introduction**

31 Dense currents are flows driven by the difference in density between two fluids due to a gradient  
32 in the temperature or the concentration fields. In the environment, these kind of flows widely  
33 occur both in the atmosphere (e.g. sea breeze, katabatic currents) and in the oceans (i.e. oceanic  
34 overflows) (see Simpson 1997, for a review).

35 Overflows are dense water masses intruding into a lighter ambient fluid and often moving over  
36 a sill or through a bathymetric constriction. Sources of these dense water masses are generally  
37 located at high latitudes where the strong atmospheric cooling causes a temperature reduction,  
38 the formation of ice, and brine rejection, which induces an increase in salinity. One example is  
39 Nordic Seas waters flowing into the North Atlantic Ocean through Denmark Strait (Girton and  
40 Sanford 2003) and the Faroe Bank Channel (Mauritzen et al. 2005), forming North Atlantic Deep  
41 Water (NADW), a fundamental component of the thermohaline circulation. Generation of dense  
42 waters is also observed in marginal seas where evaporation causes an increase in density, e.g. the  
43 Mediterranean waters flowing into the Atlantic Ocean through the Gibraltar Strait (Price et al.  
44 1993), or the Red and the Persian Sea waters spreading into the Arabian Sea (Peters et al. 2005).  
45 Oceanic overflows are observed to descend over the continental slope until they reach the ocean  
46 bottom or their level of neutral buoyancy. Overflow properties, i.e. temperature, salinity, and  
47 particle and nutrient concentrations, change during this descent due to entrainment processes,  
48 which consequently affect both the local ecosystems, as well as the global climate equilibrium  
49 through the thermohaline circulation.

50 The Earth's rotation plays a major role in the dynamics of these overflows. One of the most  
51 prominent effects is the deflection of the dense current trajectory to the right looking down-  
52 stream (in the North Hemisphere) due to the Coriolis acceleration. The momentum is mainly

53 in geostrophic balance with the effect of bottom drag resulting in a descent of the current across  
54 isobaths. The effect of the entrainment is similar to that of the bottom drag in the momentum  
55 balance, but it also modifies the continuity equation (Price and Barringer 1994). When a dense  
56 overflow or a turbidity current flows into a submarine channel, transport in the Ekman boundary  
57 layers due to the Earth's rotation induce a complex traverse circulation that strongly affects the  
58 dense current dynamics when the Ekman number is of the order of 1 and the Froude number ( $Fr$ )  
59 is subcritical (Umlauf and Arneborg 2009a,b). In particular, entrainment can be augmented by  
60 this secondary transverse circulation (Umlauf et al. 2010). For larger values of the Ekman number  
61 a similar secondary transverse flow was observed in the laboratory (Cossu et al. 2010; Cossu and  
62 Wells 2010). Furthermore, when a dense current flows down a canyon it can accelerate increasing  
63 the  $Fr$  and Reynolds ( $Re$ ) number of the flow leading to overturning and turbulence and hence an  
64 increase of the entrainment rate, as observed in the laboratory study of Wåhlin et al. (2008).

65 Entrainment processes are fundamental players in the dynamics of dense currents because they  
66 contribute to the dilution of the current, hence changing the buoyancy forces driving the motion  
67 itself. A faithful representation of overflows in climate and general circulation models requires a  
68 correct parametrization of the entrainment which is not resolved by coarse models. For this reason,  
69 entrainment and mixing processes in gravity currents have been the subject of a large number of  
70 studies which employ both numerical simulations (e.g. Chang et al. 2005; Ezer 2005; Legg et al.  
71 2006; Xu et al. 2006; Özgökmen et al. 2009; Ottolenghi et al. 2016a,b) and laboratory experiments  
72 (e.g. Hacker et al. 1996; Cenedese et al. 2004; Cenedese and Adduce 2008). A widely used  
73 entrainment parametrization was proposed by Turner (1986), based on the laboratory experiments  
74 of Ellison and Turner (1959). The entrainment rate magnitude is modeled to be a function of  
75 the Froude number and is non-zero only for supercritical flows ( $Fr^2 > 1.25$ ). Entrainment for  
76 subcritical flows was included in subsequent parameterizations (Cenedese et al. 2004; Cenedese

77 and Adduce 2010) and recently a parametrization depending on both the Froude and Reynolds  
78 numbers was proposed by Cenedese and Adduce (2010). Similar Froude (or Richardson) number  
79 based parameterizations have also been suggested for turbidity currents (Parker et al. 1987).

80 The existing entrainment parameterizations account primarily for the shear-induced entrainment  
81 at the interface between the dense flow and the ambient fluid. However, the turbulence generated  
82 by bottom roughness, which produces an enhanced drag, can be intense and may need to be consid-  
83 ered (Dallimore et al. 2001; Fernandez and Imberger 2006; Wells et al. 2010). Parameterizations  
84 accounting for both the Richardson number ( $Ri$ ) and the stresses generated at the bottom, directly  
85 related to the bed roughness, predict values of the entrainment parameter  $E$  which are in a better  
86 agreement with field measurements than the values obtained from parameterizations based only  
87 on  $Ri$  (Fernandez and Imberger 2006). In particular, the study of Fernandez and Imberger (2006)  
88 showed that at relatively high Richardson numbers ( $Ri > 10$ ) the entrainment rate was underesti-  
89 mated by parametrization written as  $E = E(Ri)$ , while the entrainment was better predicted using  
90 an entrainment formulation in the form  $E = E(C_D, Ri)$  (Hebbert et al. 1979; Dallimore et al. 2001).  
91 On the other hand, when  $Ri < 10$ , all the entrainment laws tested by the authors were in agreement  
92 with the entrainment measured in the field. During a flow regime governed by a balance between  
93 drag and buoyancy forces, the influence of  $Ri$  decreases when the roughness becomes large and  
94 the influence of the bottom stress on the entraining interface increases. Bottom roughness and  
95 an oscillating sloping bottom have also been used to investigate the effect of bottom boundary  
96 mixing on a dense gravity current flowing down a slope. An increase in background turbulence  
97 was observed to increase the height of the dense current and decrease of the front speed (Noh and  
98 Fernando 1991, 1992).

99 In the study of Negretti et al. (2008), it was observed that the rough bottom affects the dynamics  
100 of the flow via two contrasting mechanisms: the additional turbulence caused by the rough bottom

101 enhances entrainment, but, at the same time, the rough bottom causes a decrease in the current  
102 velocity, inhibiting the formation of large-scale turbulent structures due to shear instability, with a  
103 consequent reduction in entrainment at the interface. Similar findings were also presented in the  
104 studies of Nogueira et al. (2013, 2014), which focused on lock-release gravity currents flowing  
105 over a natural rough bed. Using numerical simulations, Özgökmen et al. (2004) found that the  
106 entrainment in bottom gravity currents flowing over a complex topography was enhanced when  
107 compared to that in a current moving over a smooth surface. As a consequence, bottom rough-  
108 ness influences the overflow product distribution in that the highest density classes are removed  
109 and the level of neutral buoyancy is reached higher in the water column (Özgökmen and Fischer  
110 2008). The dynamics of gravity currents flowing over a rough bottom have also been studied in the  
111 context of flows within aquatic vegetation (Luharl et al. 2008; Nepf 2012). In these studies, the di-  
112 mensionless parameter characterizing the roughness elements distribution was correlated with the  
113 size of the turbulent structures arising in the flow. Following Luharl et al. (2008) and Nepf (2012),  
114 the frontal area per volume  $a$  and the frontal area per bed area  $ah$  are defined as  $a = \frac{d}{\Delta S^2}$ , where  $d$ ,  
115  $h$  and  $\Delta S$  are the diameter, the height and the spacing of the roughness elements, respectively. In  
116 particular,  $\Delta S$  is defined as the distance between the center of two adjacent elements. In the cited  
117 investigations, it was observed that for  $ah \geq 0.1$  a shear layer was generated in the flow on top of  
118 the roughness elements, with the consequent formation of turbulent structures. These vortices can  
119 penetrate to different depths in the roughness region, for different values of  $ah$ . The larger  $ah$  the  
120 deeper the penetration of the shear induced vortices, hence the homogenization and mixing of the  
121 fluid within the roughness elements is regulated by  $ah$ .

122 The aim of the present laboratory study is to investigate the effects of a rough bottom on the en-  
123 trainment in dense currents propagating under conditions similar to those of Cenedese and Adduce  
124 (2008). In particular, the entrainment in a dense current flowing down a rough sloping bottom in a

125 rotating environment is examined by varying the inclination of the slope, the height of the rough-  
126 ness elements and their distribution on the slope. In the ocean, bottom roughness presents a wide  
127 variety of scales, from few tenths of centimeters (e.g. Fernandez and Imberger 2006), to few tenths  
128 of meters (e.g. Hernández-Molina et al. 2006; Hanquiez et al. 2007), and up to few hundreds of  
129 meters when looking at the multiple fractures characterizing the Reykjanes Ridge (e.g. Keeton et al.  
130 1997). The height of the dense gravity currents flowing over these roughness elements is highly  
131 variable too, and although the major overflows are several hundreds of meters thick, thin dense  
132 currents can result from branching of these larger overflows into canyons or around ridges (Sher-  
133 win and Turrell 2005), and can be found in marginal basins like the Baltics (Umlauf and Arneborg  
134 2009a,b), but also in lakes (Dallimore et al. 2001; Fernandez and Imberger 2006) and in reservoirs  
135 (Hebbert et al. 1979; Fernandez and Imberger 2006). Hence, to cover the wide range of scales  
136 characterizing the roughness elements and the thickness of the gravity currents in the ocean, in the  
137 current study we investigate gravity currents having a height which will systematically vary from  
138 being smaller than the roughness elements, characteristic of flow within aquatic vegetation (e.g.  
139 Nepf 2012), to much larger than the roughness elements, as is the case for the larger overflows or  
140 overflows in reservoirs, where both the roughness and current height can be small but give a large  
141 ratio of current to roughness height (e.g. Fernandez and Imberger 2006).

142 This paper is organized as follows: In section 2 the experimental apparatus is described together  
143 with the experimental technique followed to perform the laboratory experiments. The entrainment  
144 parameter and the dimensionless numbers characterizing the flow are defined in sections 3 and 4,  
145 respectively. Sections 5 and 6 discuss the behavior of the dense current as it moves downslope  
146 and the different flow regimes observed, respectively. Sections 7 and 8 illustrate the entrainment  
147 parameter dependence on the relevant dimensionless numbers. The results are discussed in section  
148 9, and the conclusions are given in section 10.

## 149 2. Laboratory experiments

### 150 a. Experimental apparatus

151 A total of 68 experiments were performed using an experimental technique similar to Cenedese  
152 and Adduce (2008). Dense gravity currents were generated in a glass square tank, 60 cm high  
153 and 60 cm wide, by the constant supply of salted and dyed water at a measured density  $\rho_1$  into  
154 an ambient fluid at density  $\rho_0 < \rho_1$  (Fig. 1). The tank was placed on a 1 m diameter rotating  
155 turntable with a constant rotation rate, characterized by a Coriolis parameter  $f = 1 \text{ s}^{-1}$ . A sloping  
156 bottom was placed inside the tank forming an angle  $\theta$  with the horizontal. The experiments were  
157 performed by varying the slope  $s = \tan \theta$  between 0.4 - 8, while the flow rate of dense fluid  
158  $Q_0 = 2.5 \text{ cm}^3 \text{ s}^{-1}$  was kept constant. The dense fluid was pumped through a plastic tube into a  
159 small box with a sponge inside, i.e. the source of dense water, located on the top-right hand side  
160 of the sloping bottom (Fig. 1), at a depth  $H_0$  from the free surface.  $H_0$  took values of 10 cm for  
161  $0.4 \leq s \leq 2$  and 5 cm for  $3 \leq s \leq 8$ . Small rigid vertical cylinders were attached to the slope in order  
162 to investigate the effect of a rough bottom on the flow dynamics. The cylinders were characterized  
163 by a diameter  $d = 0.5 \text{ cm}$  which was kept fixed, an height  $h$  which assumed three values 0.1 cm,  
164 0.3 cm and 0.5 cm, and a spacing  $\Delta S$  which assumed two values  $\Delta S = 0.8 \text{ cm}$  (*dense* configuration)  
165 and  $\Delta S = 1.6 \text{ cm}$  (*sparse* configuration). In some experiments the cylinders were higher than the  
166 current depth, while in others they were smaller (section 7). The *smooth* configuration, i.e. a  
167 sloping bottom with no roughness elements, was also tested for all the considered values of  $s$  for  
168 comparison with Cenedese and Adduce (2008).

169 The top-view of the experiments was recorded in the rotating system of reference by a camera  
170 fixed on the top of the rotating table. The duration of each experiment and the time the current  
171 took to reach the bottom of the slope were recorded by two stopwatches. After the dense current

172 propagated through and/or over the rough bottom, the dense fluid was collected into a pocket  
173 located at the end of the slope and solid vertical walls surrounding the slope assured the absence  
174 of lateral leakages (Fig. 1). A more detailed description of the experimental apparatus can be  
175 found in Cenedese and Adduce (2008).

### 176 *b. Description of the experimental procedure*

177 After the ambient fluid reached solid body rotation, the pump was turned on and the experiment  
178 started. The dense current was generated and propagated down the slope through and/or over  
179 the rough bottom, entraining ambient fluid and diluting. The trajectory of the dense current was  
180 deflected towards the right, looking downslope, by the Coriolis acceleration. The time taken by  
181 the dense current to reach the end of the slope,  $\delta t$ , was recorded by one of the two stopwatches.  
182 As in Cenedese and Adduce (2008), in order to investigate the entrainment occurring along the  
183 descent of the current, and minimize the influence of the entrainment occurring near the head of  
184 the current, the experiments lasted for a time  $\Delta T \gg \delta t$ . Hence, the pump continued to provide  
185 dense fluid to the system until the dense fluid in the pocket reached a fixed vertical level, then the  
186 pump was turned off. The second stopwatch recorded the duration of the entire experiment  $\Delta T$ .

### 187 **3. Entrainment parameter**

188 The focus of the experiments was to quantify the volume of ambient fluid entrained by the dense  
189 current. The volume  $V$  of dense fluid collected into the pocket was approximately the same in each  
190 experiment, since the dense fluid level reached a fixed height  $H$  inside the pocket after the time  
191  $\Delta T$ . Error bars are evaluated considering the possible variations of the fluid volume collected into  
192 the pocket, due to the difference between the value of the fixed vertical level  $H$  and the real steady  
193 height reached by the dense fluid after its adjustment along the width of the tank ( $\pm 0.5$  cm). The

194 possible errors in the evaluation of  $V$  affect all the derived quantities discussed below. The volume  
 195  $V$  is composed of dense fluid of density  $\rho_1$  and ambient fluid of density  $\rho_0$  entrained during the  
 196 descent of the dense current.

$$V = (Q_e + Q_0) \Delta T, \quad (1)$$

197 where  $Q_e$  is the entrainment volume flux into the dense current.

198 The average entrainment velocity  $w_e$  is defined as

$$w_e = \frac{Q_e}{A} = \frac{1}{A} \left( \frac{V}{\Delta T} - Q_0 \right), \quad (2)$$

199 where  $A$  is the area on the slope covered by the dense current, evaluated by an image-analysis of  
 200 the top-view pictures recorded by the camera. The bulk velocity of the dense current  $U_m$  is defined,  
 201 following Cenedese and Adduce (2008), as

$$U_m = \frac{L}{\delta t}, \quad (3)$$

202 where  $L$  is the length of the path followed by the current and  $\delta t$  is the time taken by the dense fluid  
 203 to reach the end of the slope. The entrainment parameter  $E$  is finally defined as

$$E = \frac{w_e}{U_m} = \frac{\delta t}{L A} \left( \frac{V}{\Delta T} - Q_0 \right). \quad (4)$$

204 Considering  $n = \Delta T / \delta t$  as the hypothetical number of times the dense current has traveled down  
 205 the slope during each experiment, it is possible to evaluate the mean height of the gravity current,  
 206  $H_m$ . In particular, the volume of fluid  $V$  is considered to be distributed over the area  $A$ , and taking  
 207 into account the volume  $V_c$  occupied by the cylindrical roughness elements (with  $V_c$  varying for  
 208 each roughness and depending on  $A$ ):

$$H_m = \frac{\frac{V}{\Delta T} + V_c}{A} = \frac{\frac{V}{n} + V_c}{A}. \quad (5)$$

209 During each experiment the height of the dense current, approximately half way down the slope,  
 210 was observed and recorded. However, the precision of this measurement was poor and we only  
 211 used it to have a visual confirmation of the values obtained for  $H_m$ . Furthermore, assuming the  
 212 fluid in the dense current is homogeneous, the density of the fluid inside the pocket at the end of  
 213 the experiment is given by

$$\rho_p = \frac{\rho_1 Q_0 + \rho_0 Q_e}{Q_0 + Q_e}, \quad (6)$$

214 and the mean reduced gravity  $g'_m$  of the dense current is defined as

$$g'_m = g \frac{\rho_{mean} - \rho_0}{(\rho_1 + \rho_0)/2}, \quad (7)$$

215 being  $\rho_{mean} = (\rho_1 + \rho_p)/2$  the mean value between the densities at the beginning and at the end  
 216 of the slope.

#### 217 4. Dimensionless parameters

218 The discussion of the dimensionless parameters characterizing the bottom roughness is similar  
 219 to that of Cenedese et al. (2016) as follows in the next paragraph. The elevation density,  $\mu$ , is  
 220 defined by

$$\mu = \frac{A_E}{A_{TE}} = \frac{d}{\Delta S}, \quad (8)$$

221 where  $A_E$  is the area of the field covered by the cylinders in elevation as seen by the advancing  
 222 current and  $A_{TE}$  is the total area of the field in elevation (measured to the top of the cylinders), as  
 223 shown in Fig. 2(a);  $\sigma$ , the plan density, is defined by

$$\sigma = \frac{A_P}{A_{TP}} = \frac{\pi}{4} \gamma \mu^2, \quad (9)$$

224 where  $A_P$  is the area of the base covered by the cylinders in plan,  $A_{TP}$  is the total area of the base  
 225 in plan and  $\gamma = \frac{\Delta S_x}{\Delta S_y} = \frac{2}{\sqrt{3}}$  for our configuration (Fig. 2b); and  $\alpha$ , the aspect ratio of the roughness  
 226 elements, is defined by

$$\alpha = \frac{h}{d}. \quad (10)$$

227 The above roughness parameters for the sparse configuration were  $\sigma = 0.08$  and  $\mu = 0.30$  and for  
 228 the dense configuration were  $\sigma = 0.34$  and  $\mu = 0.61$ . For our particular configuration in which  
 229 each element is equidistant to the surrounding ones, the parameters  $\sigma$  and  $\mu$  are not independent,  
 230 however this is not the case when the roughness elements are not equidistant from each other. The  
 231 value of  $\alpha$  was 0.2, 0.6 and 1 for each configuration. The above parameters can be combined to  
 232 give the roughness frontal area per bed area parameter introduced by Nepf (2012)

$$ah = \gamma \frac{dh}{\Delta S^2} = \gamma \alpha \mu^2 = \frac{4}{\pi} \alpha \sigma. \quad (11)$$

233 The values of  $a$  and  $ah$  for the roughness used are summarized in Table 1. An additional non-  
 234 dimensional number is the ratio of the cylinder height to the current depth

$$\lambda = \frac{h}{H_m}, \quad (12)$$

235 which in the present experiments varied between 0.08 and 1.47. It is important to note that for  
 236  $\lambda > 1$  the array of cylinders represents a series of obstacles for the current and not a bottom  
 237 roughness. However, for simplicity we also call the array of cylinders ‘roughness elements’ also  
 238 for the experiments having  $\lambda > 1$ .

239 Finally, the Reynolds and the Froude numbers are defined as

$$\text{Re} = \frac{H_m U_m}{\nu}, \quad (13)$$

$$\text{Fr} = \frac{U_m}{\sqrt{g'_m H_m \cos \theta}}, \quad (14)$$

240 with  $\nu$  the kinematic viscosity of water ( $\nu = 10^{-2} \text{ cm}^2 \text{ s}^{-1}$ ). The Froude and Reynolds numbers  
 241 varied between  $\text{Fr} = 0.43 - 2.57$  and  $\text{Re} = 13 - 134$ . It is important to note that the values of the  
 242 Reynolds number are lower than in similar studies investigating the dynamics of a dense current  
 243 over a smooth bottom (e.g. Ellison and Turner 1959; Parker et al. 1987; Cenedese and Adduce  
 244 2008). Hence, the values of the entrainment parameter  $E$  are also expected to be lower than in the  
 245 studies mentioned above, given the Reynolds number dependence of the entrainment parameter  
 246 (e.g. Cenedese and Adduce 2010).

## 247 **5. Downslope flow mechanisms**

248 In a recent study, Cenedese et al. (2016) investigated a non-rotating lock-exchange dense gravity  
 249 current propagating over a bottom roughness made of an array of vertical rigid cylinders having  
 250 the same geometrical distribution as in the present study (Fig. 1b). The larger dimension of  
 251 their apparatus allowed them to investigate the details of the flow between the cylinders and they  
 252 observed that when a sparse configuration of roughness elements is present, the dense current  
 253 propagates between the cylinders which act on the current more as obstacles than as a rough bottom

254 boundary, while for a dense configuration, the dense current rides on top of the cylinders. The  
255 experiments of Cenedese et al. (2016) also showed that for a sparse configuration the entrainment  
256 is enhanced by the vortices generated in the wake of the cylindrical obstacles, especially when the  
257 roughness element height is approximately the same as the dense current interface. Furthermore,  
258 in the dense configuration the dense fluid riding on top of the cylinders is located above the lighter  
259 ambient water between the cylinders. This configuration is convectively unstable and the dense  
260 current fluid is diluted by mixing with the lighter fluid between the cylinders.

261 The present experiments focused on the effect of bottom roughness on entrainment and the  
262 experimental apparatus was too small to clearly detect the details of the fluid propagating between  
263 the cylinders. However, for some of the experiments in the sparse configuration it was clear that  
264 the dense fluid propagated between the cylinders, while this behavior was not observed for the  
265 experiments having a dense configuration. Hence, we will make the assumption that the different  
266 behaviors observed and discussed in detail in Cenedese et al. (2016) are occurring also in our  
267 experimental set up, i.e. that the dense current propagates between and on top of the cylinders for  
268 a sparse and dense configuration, respectively.

269 The procedure followed to obtain the entrainment parameter  $E$ , discussed in section 3, utilizes  
270 the volume of the dense current at the bottom of the slope and hence does not distinguish between  
271 the entrainment of ambient waters through the current interface and the dilution of the current due  
272 to convective instability occurring in the dense configuration. Hence, hereafter by ‘entrainment’  
273 we will refer to both of the above processes contributing to the dilution of the dense current.

## 274 **6. Flow regimes**

275 As observed for a rotating dense current over a smooth sloping bottom (e.g., Cenedese et al.  
276 2004), the dense fluid exiting the source moved first down-slope and then it was deflected to the  
277 right (looking downslope) by the effect of rotation.

278 According to Cenedese et al. (2004) and Cenedese and Adduce (2008), different flow regimes  
279 can be observed during the descent of a dense current over a sloping bottom. A *laminar* regime, a  
280 *wave* regime, a *breaking-wave* regime or a *turbulent* regime develop depending on the values of Fr  
281 and Re. Cenedese and Adduce (2008) selected specific Re to mark the transition between regimes:  
282 for  $Re < 14$  laminar and waves regimes were observed, for  $14 \leq Re \leq 40$  the breaking-waves  
283 regime was detected, while the turbulent regime occurred for  $Re > 40$ .

284 Table 2 shows the frequency of occurrence of the different flow regimes in the present study for  
285 selected intervals of the Reynolds number. A laminar or a waves regime developed in  $\sim 90\%$  of the  
286 experiments having  $Re < 39$ ; 80% of the experiments with  $39 \leq Re \leq 85$  behaved in a breaking-  
287 waves regime; while for  $Re > 85$ ,  $\sim 95\%$  of the experiments displayed a turbulent regime. Thus,  
288 for dense currents flowing over and/or through a rough bottom, larger Re than those observed for  
289 dense currents propagating on a smooth bottom have to be reached in order to observe the passage  
290 through the different flow regimes. To characterize the different regimes including the influence of  
291 the Froude number, we determined the transition between regimes using the buoyancy Reynolds  
292 number,  $Fr^2Re$ . This non-dimensional number is an important parameter widely used to describe  
293 stratified turbulent mixing (Riley and de Bruyn Kops 2003; Hebert and de Bruyn Kops 2006).  
294 The buoyancy Reynolds number must be above a critical value, typically taken to be 25-30, for  
295 stratified turbulence mixing to be active. The frequency of occurrence of the flow regimes in terms  
296 of  $Fr^2Re$  is: laminar and waves regimes were generally observed for  $Fr^2Re < 50$  (in  $\sim 80\%$  of

297 the experiments), the breaking-waves regime developed for  $50 \leq Fr^2Re \leq 180$  (in 75% of the  
298 experiments) and fully developed turbulent patterns were observed for  $Fr^2Re > 180$  (in  $\sim 90\%$  of  
299 the experiments).

## 300 **7. Entrainment dependence on slope angle and roughness height**

301 The inclination of the sloping bottom is an important parameter which strongly affects the cur-  
302 rent velocity and hence the flow dynamics. Different flow regimes were observed to develop  
303 when varying  $s$ , with relevant consequences on the entrainment processes. For small values of  $s$   
304 ( $0.4 \leq s \leq 0.85$ ) the laminar and the non-breaking waves regimes were observed in  $\sim 90\%$  of the  
305 experiments, for all values of  $ah$  tested, and, as expected, the entrainment in these regimes was  
306 generally lower than for the other regimes (Fig. 3). In these regimes the interface between the  
307 dense and the light fluids is sharp and only slightly perturbed by the waves, hence a low amount  
308 of ambient fluid is entrained in the dense current. For intermediate values of  $s$  ( $1 \leq s \leq 3$ ) the  
309 breaking-waves regime was usually observed (in  $\sim 65\%$  of the experiments) independently of  
310 the roughness parameter  $ah$ . This regime is associated with a large amount of entrainment (Fig.  
311 3) caused by the wave crests breaking and propagating downstream with the current (Cenedese  
312 and Adduce 2008). Finally, for high inclinations of the slope ( $s \geq 4$ ), a fully developed turbulent  
313 regime was observed in  $\sim 90\%$  of the experiments and the highest values of  $E$  are distinctly de-  
314 tectable and are approximately constant for increasing value of  $s$ , confirming that a fully developed  
315 turbulent regime has been reached (Fig. 3).

316 Although the behavior described above is observed for all of the different roughness configu-  
317 rations, some differences in entrainment were also observed for varying  $ah$  and  $\lambda$ . In Fig. 3 and  
318 subsequent figures, white symbols mark the low-value  $ah$  cases, gray markers are used for the  
319 intermediate-value  $ah$  cases and black symbols represent the high-value  $ah$  cases. The experi-

320 ments over a smooth bottom (Fig. 3, open circles) are generally characterized by the lowest values  
 321 of  $E$  for all slopes. For  $s < 1$  the largest values of  $E$  are usually observed in the intermediate  
 322 roughness cases (gray symbols in Fig. 3), while the lowest values of  $E$  are associated with the  
 323 lowest  $ah = 0.02$ , the sparse configuration case in which the elements are, in general, much lower  
 324 than the dense current height (Fig. 4). For  $s \geq 1$ , the largest entrainment is, in general, detected in  
 325 the  $h = 0.1$  cm cases (white triangles and gray stars in Fig. 3).

326 The ratio between the height of the cylinders and the height of the current  $\lambda = h/H_m$  represents  
 327 another important parameter. According to eq. 5, an increase of the entrainment  $E$  leads to an  
 328 increase in  $H_m$  and thereby a decrease in  $\lambda$ , for a fixed value of  $h$  (Fig. 4). For fixed values  
 329 of  $h$ , the sparse roughness configurations ( $\Delta S = 1.6$  cm) are in general characterized by lower  
 330 heights of the gravity current than the corresponding dense configuration case ( $\Delta S = 0.8$  cm).  
 331 This behavior can be explained both by the lower value of  $V_c$  for the sparse configuration which  
 332 decreases  $H_m$  (eq. 5), and by the fact that in the sparse configuration the current flows downslope  
 333 propagating between the roughness elements, while for the dense configuration the current rides  
 334 on top of the cylinders and mixes with the lighter fluid between the cylinders (Cenedese et al.  
 335 2016), consequently increasing the total current height. In some of the cases with  $h = 0.5$  cm  
 336 the height of the current is even lower than the roughness elements, i.e.  $1/\lambda < 1$  (gray triangles  
 337 and black stars in Fig. 4). However, for approximately  $1/\lambda \gtrsim 3$  the difference in  $H_m$  between  
 338 the experiments having the same  $h$  in dense and sparse configurations is negligible. For these  
 339 experiments the current is significantly higher than the roughness elements, hence the difference  
 340 in  $V_c$  between the dense and sparse configuration is negligible compared to the total volume of the  
 341 current  $V$  producing a similar value of  $H_m$ , as indicated by eq. 5.

342 The maximum values of  $E$  for each configuration are observed to increase with decreasing  $\lambda$   
 343 (Fig. 4). In particular, the highest values of the entrainment are  $E \sim 0.011$  for  $h = 0.3$  cm, and

344  $E \sim 0.016$  for  $h = 0.1$  cm. With the exception of a few experiments having  $h = 0.1$  cm, in general  
345 the height of the current is comparable to that of the roughness elements, i.e.  $\lambda \sim 1$ . Hence, we  
346 expect the vortices generated in the wake of the cylinders in the sparse configuration to enhance  
347 the entrainment of ambient water into the current. It is important to note that the values of  $E$  in the  
348 present experiments are smaller than those found in similar experiments investigating entrainment  
349 in a dense current flowing down a smooth bottom (e.g. Ellison and Turner 1959; Parker et al. 1987;  
350 Cenedese and Adduce 2008) due to the reduced values of the Reynolds number.

## 351 **8. Entrainment dependence on Froude and Reynolds numbers**

352 The dependence of the entrainment parameter on  $Fr$  is shown in Fig. 5a where, in general, larger  
353 values of  $E$  are observed for larger  $Fr$ , for a constant value of  $ah$ . However, the data in Fig. 5a show  
354 a considerable scatter which can be partially explained when looking at the different values of  $ah$   
355 (indicated by the different symbols in Fig. 5a). Looking at the white, gray, and black symbols in  
356 Fig. 5a, representing the small, intermediate and large values of  $ah$ , respectively, one can notice  
357 that while the  $Fr$  decreases with increasing  $ah$  the range of values of  $E$  is approximately the same,  
358 i.e. black symbols are shifted toward the left compared to the white symbols in the  $Fr$ -axis, but are  
359 approximately at the same location on the  $E$ -axis. As discussed in Section 9, this can be explained  
360 by the different mechanisms at play associated with different values of  $ah$ .

361 The large scatter between  $Fr$  and  $E$  visible in Fig. 5a is also due to the different Reynolds  
362 numbers, as discussed previously in Cenedese and Adduce (2008). For a fixed  $Fr$ , larger values of  
363  $E$  are observed as  $Re$  increases. For example, for  $Fr \sim 1.2$ ,  $Re \sim 13$  in the smooth case (white  
364 circle at the bottom of the figure),  $Re \sim 33$  in the  $ah = 0.11$  case (gray right side triangle) and  $Re$   
365  $\sim 110$  in the  $ah = 0.27$  case (black square at the top of the figure).

366 An almost linear dependence of  $E$  on  $Re$  has been observed (Fig. 6), in agreement with Cenedese  
367 and Adduce (2008). The largest values of  $Re$  and  $E$  are observed for  $ah = 0.02$  and  $ah = 0.08$ ,  
368 which are the roughness values for  $h = 0.1$  cm. As expected, the largest  $E$  are associated with the  
369 turbulent regime observed for  $Re > 85$  and for the wave-breaking regime observed for  $39 \leq Re$   
370  $\leq 85$  (black dashed lines in Fig. 6).

371 While Fig. 5a clearly shows that the Froude number generally decreases as  $ah$  increases, due  
372 in most cases to a decrease of  $U_m$ , the Reynolds number is not clearly sensitive to the value of  $ah$   
373 as all values of  $ah$  span a similar range in Reynolds number (Fig. 6). The independence of the  
374 Reynolds number on the roughness parameter  $ah$  can be explained by the fact that for large  $ah$   
375 the bulk velocity is observed to be lower than for high  $ah$  while, in general, the value of  $H_m$  is  
376 larger, hence resulting in a value of the Reynolds number which is not sensitive to the roughness  
377 parameter.

378 Furthermore, the value of the entrainment parameter is more sensitive to the value of  $Re$  than  
379  $Fr$ , i.e. Fig. 5b shows that similar values of  $E$  are associated with similar values of  $Re$ , while  
380 the Froude number varies from a factor of two for the highest  $Re$  (gray squares in Fig. 5b), to  
381 more than half an order of magnitude for the lowest values of  $Re$  (gray triangles in Fig. 5b). This  
382 weaker dependence of the entrainment parameter on  $Fr$  is not as prominent for a dense current  
383 flowing over a smooth bottom, as illustrated by our data and the data of Cenedese and Adduce  
384 (2008) in Fig. 5b. The value of  $E$  can be the same for different values of  $Fr$  also for a dense  
385 current flowing over a smooth bottom, however the ranges of  $Fr$  where this is observed are much  
386 smaller than in the case of a dense current over a rough bottom, especially for the lowest values  
387 of  $Fr$ . For large  $Fr$ , i.e.  $Fr > 2$ , the parameterizations of Turner (1986) and Cenedese and Adduce  
388 (2010) suggest that  $E$  is weakly dependent on  $Fr$ , as indicated by the flattening of the curves in  
389 Fig. 5.

390 A possible explanation for the (low  $Fr$ ) weaker dependence of the entrainment parameter on  $Fr$   
391 is that, in the presence of a rough bottom, the entrainment process is influenced not only by shear  
392 instability due to density differences, but some entrainment occurs also via the vortices created  
393 in the wake of the cylinders and convective mixing (as observed by Cenedese et al. 2016, and  
394 discussed in Sec. 5). The above mechanisms for entrainment are expected to be more effective  
395 near the head of the current (Cenedese et al. 2016) while our measurements are representative of  
396 the entrainment occurring once a quasi-steady state regime is reached in the body of the current.  
397 Hence, we expect our entrainment data to be influenced both by the above mechanisms and also  
398 by shear instability, retaining a small, and possibly not as clear, dependence of the entrainment  
399 parameter on the Froude number.

400 In order to consider the influence of both  $Fr$  and  $Re$ , the entrainment parameter versus the buoy-  
401 ancy Reynolds number,  $Fr^2Re$ , is plotted in Fig. 7, where the increase of  $E$  at the increase of  $Fr^2Re$   
402 for each  $ah$  is clearly visible. For fixed values of  $Fr^2Re$ , the smooth and the low  $ah$  cases (white  
403 markers) are characterized by lower  $E$  than the intermediate  $ah$  cases (gray markers) and the high  
404  $ah$  cases (black markers). As previously observed in Fig. 6, Fig. 7 shows the largest values of  $E$   
405 occurring in the  $ah = 0.02$  and  $ah = 0.08$  cases, which, in general, are characterized by the largest  
406 value of  $Fr^2Re$ .

407 For low and intermediate values of  $Fr^2Re$  the increase of  $E$  at the increase of  $ah$  for fixed value of  
408  $Fr^2Re$  is clearly visible, while for large values of  $Fr^2Re$ , a fully developed turbulent regime occurs  
409 and high values of  $E$  are always detected independently of  $ah$ , albeit  $E$  is increased compared to  
410 the smooth bottom cases. Finally, given the observed independence of the Reynolds number on  
411 the value of  $ah$  (Fig. 6), the decrease of  $Fr^2Re$  with the increase in  $ah$  is due to the decrease in  $Fr$   
412 with increasing  $ah$  observed in Fig. 5a.

## 413 9. Discussion

414 The results illustrated in the previous sections clearly show that the presence of roughness ele-  
415 ments strongly influences the dynamics of a dense current flowing down a sloping bottom, both  
416 in terms of the dense current velocity and the entrainment of ambient waters. The presence of a  
417 rough bottom enhances the drag exerted on the dense current (e.g. Tanino et al. 2005; Tanino and  
418 Nepf 2008; Zhang and Nepf 2008) with the consequent decrease in the dense current velocity,  $U_m$ .  
419 Hence, for fixed values of  $Q_0$ ,  $g'_0$  and  $s$  an increase in  $ah$  caused a reduction of the Froude number,  
420 while the Reynolds number was found to be generally insensitive to the value of  $ah$  due to the  
421 increase of  $H_m$  associated with the decrease in  $U_m$  observed for large values of  $ah$ .

422 Previous studies (e.g. Ellison and Turner 1959; Cenedese and Adduce 2008) suggest that the  
423 magnitude of the entrainment is uniquely related to the Fr and Re of the flow, a concept that allows  
424 the development of parameterizations for entrainment based on the relevant non-dimensional pa-  
425 rameters (Fig. 5 dotted, solid, and dashed lines). However, our results suggest that this may not be  
426 the case in the presence of a rough bottom (e.g., Fig. 5), indicating that additional non-dimensional  
427 parameters may need to be considered to correctly parameterize entrainment when a rough bottom  
428 is present. Additional non-dimensional parameters are necessary to take into consideration the  
429 new dynamics affecting entrainment that arise in the presence of a rough bottom. In particular, the  
430 presence of the roughness elements has been shown to inhibit the formation or the growth of the  
431 turbulent structures generated by shear instability at the interface between the dense and ambient  
432 fluids (Negretti et al. 2008), and entrainment can be enhanced by the vortices generated in the  
433 wake of the cylinders in a sparse configuration or by the convective instability occurring in a dense  
434 configuration (Cenedese et al. 2016).

435 The reduction of the growth rate of the turbulent structures generated by shear instability at the  
436 interface between the dense and ambient fluids (Negretti et al. 2008) may explain why the tran-  
437 sition between the different flows regimes for a dense current over a rough bottom occurred for  
438 larger  $Re$  than those observed in the smooth bottom experiments (Section 6). We also expect that  
439 this reduction is going to be larger for increasing values of  $h$ . Hence, in general, the largest values  
440 of  $E$  are observed for the experiments having  $h = 0.1$  cm, or lower  $ah$  (Figs. 3 and 7), because  
441 the small height of the cylinders does not inhibit the formation of turbulent disturbances at the  
442 interface between the two fluids and the breaking-waves and the turbulent regimes can develop;  
443 nevertheless, the presence of the roughness slightly increases the values of the entrainment when  
444 compared to the smooth cases. When in the laminar and non-breaking waves regimes the opposite  
445 happens and the lowest entrainment, similar to that in the smooth bottom experiments (Fig. 3), is  
446 observed for the lowest value of  $ah$  because shear instability is not occurring and the roughness el-  
447 ements do not substantially enhance entrainment compared with the smooth bottom cases because  
448 they are too small.

449 The decrease in the dense current velocity due to bottom drag explains the decrease in  $Fr$  and  
450  $Fr^2Re$  with increasing  $ah$ , i.e. the horizontal shift of the symbols having the same color in Figs.  
451 5a and 7, while the different mechanisms enhancing entrainment observed by Cenedese et al.  
452 (2016) can clarify why the range of  $E$  is approximately the same for all  $ah$ . In the presence of a  
453 dense rough bottom (i.e. larger values of  $ah$ ) the current is strongly decelerated with a consequent  
454 reduction of the Froude number. However, the convective instability arising within the roughness  
455 elements (Cenedese et al. 2016) produces a relatively large  $E$  for such low  $Fr$  or  $Fr^2Re$  when  
456 compared with previous experiments. In Fig 5a the parameterization proposed by Cenedese and  
457 Adduce (2010) is indicated by the dotted, solid, and dashed lines for  $Re = 10, 100$  and  $1000$ ,  
458 respectively. These curves were obtained by fitting an extensive data set of laboratory experiments

459 conducted in this range of  $Re$  for dense currents over a smooth bottom (Fig 5b). Fig. 5b shows that  
460 for low  $Fr$  the value of  $E$  in the presence of a rough bottom (gray solid symbols) is significantly  
461 larger than for the smooth bottom experiments (blue open symbols) parameterized by the dotted,  
462 solid, and dashed lines. The gray symbols in Figs. 5a and 7 have, in general, lower  $Fr$  and  $Fr^2Re$   
463 than the smooth cases and white symbols due to the enhanced drag generated by the roughness  
464 elements. In these experiments entrainment is likely enhanced by the vortices generated in the  
465 wake of the cylinders and the range of values for  $E$  is comparable to that in the experiments  
466 having larger  $Fr$  or  $Fr^2Re$  (Fig. 5a and 7).

467 In summary, the presence of a rough bottom affects the dynamics of the dense current by both  
468 decreasing the velocity of the flow, and consequently the Froude number (Figs. 5 and 7) and by  
469 increasing the entrainment, for fixed values of  $Fr^2Re$ , with increasing  $ah$ , due to two different  
470 mechanisms, the vortices generated in the wake of the cylinders enhancing the entrainment of am-  
471 bient waters through the current interface (subset of gray symbols), and the convective instability  
472 mixing the ambient waters between the cylinders with the dense current moving on top of it (black  
473 symbols) .

474 In the present study the effect of rotation on the entrainment was not investigated. We choose to  
475 reproduce the experiment of Cenedese and Adduce (2008) and focus exclusively on the effects of  
476 a rough bottom on the dynamics regulating the entrainment, while keeping the Coriolis parameter  
477 constant. Previous laboratory studies (e.g., Cenedese et al. 2004) showed that rotational effects  
478 can cause the generation of cyclonic eddies above the dense current, but the entrainment in this  
479 *eddy* regime was small when compared to the entrainment in dense currents in the wave or tur-  
480 bulent regimes (Cenedese and Adduce 2008). Rotational effects strongly modify the trajectory of  
481 the dense current and the current velocity, ultimately influencing the values of  $Fr$  and  $Re$  (Section  
482 1). However, as discussed in detail in Cenedese and Adduce (2010), we believe that when a dense

483 current descends a slope, i.e. not in a submarine channel, ‘local’ mixing is not affected by rotation  
484 directly, given that the turnover time scale of the turbulent eddies is much faster than the inertial  
485 period. The rotating experiments of Wells (2007) show entrainment values almost indistinguish-  
486 able from those obtained in the non-rotating experiments of Ellison and Turner (1959), providing  
487 supporting evidence for this assumption.

## 488 10. Summary and Conclusions

489 The entrainment in a dense current flowing down through and/or over a rough bottom in a rotat-  
490 ing system was investigated using laboratory experiments. The influence on the entrainment of the  
491 slope angle and the spacing and the height of the bottom roughness elements were investigated.  
492 The entrainment parameter dependence on the relevant dimensionless numbers, i.e. the slope  $s$ ,  
493 the ratio  $\lambda$ , the Froude and Reynolds numbers and the buoyancy Reynolds number,  $Fr^2Re$ , was  
494 discussed. As in Cenedese et al. (2016), in the *sparse* configuration the dense current propagated  
495 between the cylinders. For a *dense* configuration we could not observe the flow between the cylin-  
496 ders and we assume that the dense current moved on top of the cylinders above lighter water and  
497 was subjected to convective instability with consequent enhancement of the current dilution and  
498 entrainment of ambient waters, as observed in Cenedese et al. (2016).

499 Previous studies suggest that the presence of a rough bottom affects the dynamics of the dense  
500 current and the entrainment through the development of two contrasting mechanisms: the rough  
501 elements enhance the drag exerted on the current and cause a decrease in current velocity, with  
502 an associated reduction of the Froude number, and inhibit the formation or growth of turbulent  
503 disturbances at the interface, reducing the entrainment; at the same time, the additional turbulence  
504 related to the presence of the roughness elements acts to enhance the entrainment. The latter is  
505 in the form of vortices in the wake of the cylinders enhancing the entrainment of ambient waters

506 through the current interface, for a sparse configuration, and convective instability mixing the  
507 dense current above the cylinders with the lighter water between them, for a dense configuration.

508 An increase of  $E$  with the increase of  $s$  was observed due to the transition through the flow  
509 regimes previously observed by Cenedese and Adduce (2008). For a fixed value of  $s$ , different  
510 values of the entrainment parameter were observed by varying  $ah$  (Fig. 3) because different  $Fr$   
511 and  $Re$  numbers characterized the flow. The ratio between the current height and the height of the  
512 roughness elements was  $O(1)$  for most experiments, suggesting that in the sparse configuration  
513 the vortices generated in the wake of the cylinders can enhance entrainment by engulfing ambient  
514 waters into the dense current.

515 Following the approach of Cenedese and Adduce (2008), selected values of  $Re$  and  $Fr^2Re$  were  
516 chosen as thresholds to mark the occurrence of the different flow regimes and new thresholds were  
517 identified for dense currents flowing down a rough bottom. It was found that the passage through  
518 the different flow regimes occurs for larger  $Re$  when compared to dense currents flowing down a  
519 smooth bottom, possibly because the formation of turbulent disturbances at the interface between  
520 the two layers is inhibited by the bottom roughness. The  $Fr$  number was observed to decrease  
521 with increasing  $ah$ , due to the enhanced drag and consequent decrease of the velocity of the dense  
522 current. Nevertheless, relatively high values of  $E$  were detected also for  $Fr < 1$  cases, due to the  
523 additional turbulence developed in the bottom roughness region, mainly caused by convective  
524 instability. This is qualitatively in agreement with the results of Fernandez and Imberger (2006)  
525 which showed that for large Richardson numbers ( $Ri > 10$ ) the entrainment rate was larger than  
526 that predicted by parametrization based only on  $Ri$ . Finally, the amount of ambient fluid entrained  
527 in the dense current was observed to increase with the increase of the buoyancy Reynolds number,  
528  $Fr^2Re$ . For a fixed  $Fr^2Re$ ,  $E$  was observed to increase with increasing  $ah$ . However, for larger  
529 values of  $Fr^2Re$ , in the turbulent regime, the large entrainment due to shear instability was only

530 mildly enhanced by the rough bottom and experiments with different  $ah$  present similar values of  
531  $E$ .

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650 aquatic canopy. *Water Resources Research*, **44 (8)**.

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TABLE 1. Characterization of the bottom roughness.

NAME	TYPE	$h$ (cm)	$\Delta S$ (cm)	$a$ (cm <sup>-1</sup> )	$ah$
ROUGH1	<i>dense</i>	0.5	0.8	0.91	0.44
ROUGH2	<i>sparse</i>	0.5	1.6	0.22	0.11
ROUGH3	<i>dense</i>	0.3	0.8	0.91	0.27
ROUGH4	<i>sparse</i>	0.3	1.6	0.22	0.07
ROUGH5	<i>dense</i>	0.1	0.8	0.91	0.08
ROUGH6	<i>sparse</i>	0.1	1.6	0.22	0.02

TABLE 2. Frequency of occurrence of the different flow regimes for selected intervals of Re and Fr<sup>2</sup>Re.

REGIME	Re < 39	39 ≤ Re ≤ 85	Re > 85	Fr <sup>2</sup> Re < 50	50 ≤ Fr <sup>2</sup> Re ≤ 180	Fr <sup>2</sup> Re > 180
<i>Laminar and waves</i>	90%	15%	0%	79.2%	18.8%	0%
<i>Breaking-waves</i>	10%	80%	5.6%	20.8%	75%	10.5%
<i>Turbulent</i>	0%	5%	94.4%	0%	6.2%	89.5%

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659 **Fig. 2.** (a) Schematic elevation view illustrating the area (dashed) of the field measured to the top  
660 of the cylinders  $A_{TE}$  and the area of the field  $A_E$  covered by the cylinders (gray); (b) plan  
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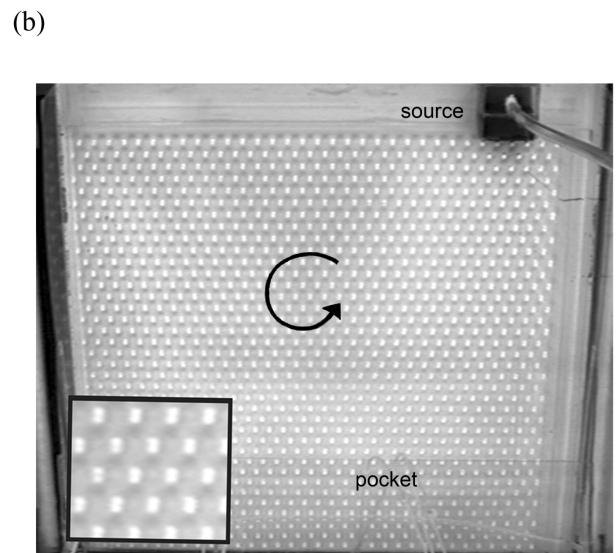
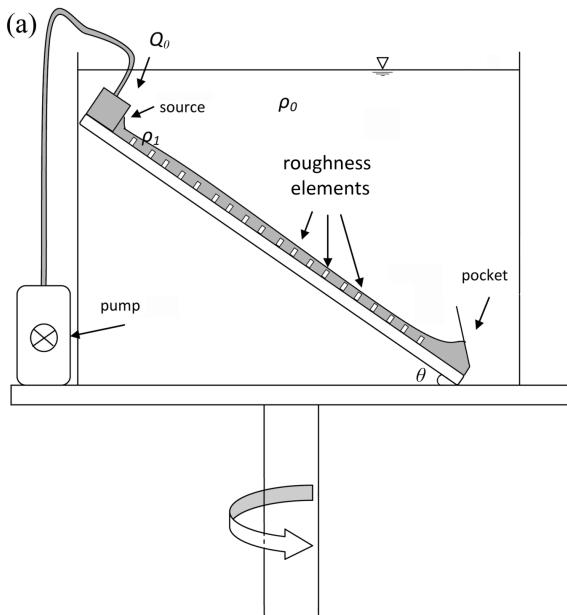
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664 ments are indicated by the open circles. White symbols are used for the low-value  $ah$  cases,  
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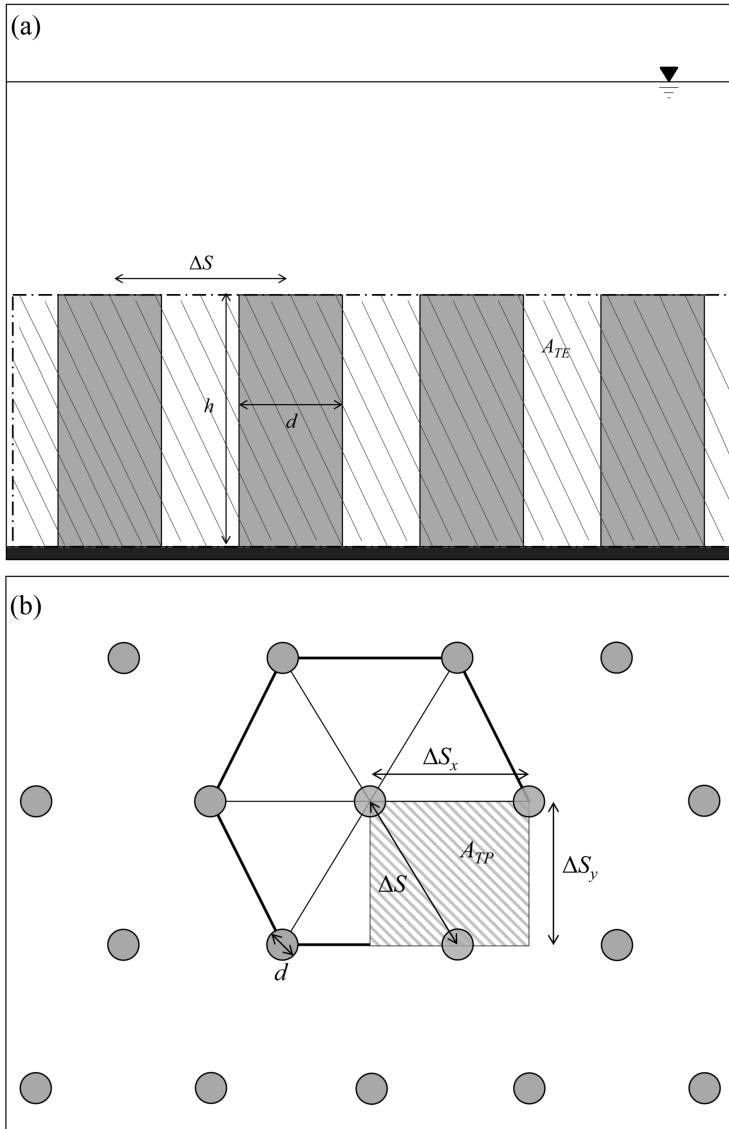
670 **Fig. 5.** Entrainment parameter dependence on the Froude number. (a) Symbols as in Fig. 3. Er-  
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673 Adduce (2010) for  $Re = 10, 100, \text{ and } 1000$ , respectively. (b) Figure adapted from Fig. 2  
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675 ment parameterization. Blue open and red solid symbols are the laboratory and field data,  
676 respectively, used to obtain the coefficients of Cenedese and Adduce (2010) entrainment  
677 parameterization represented by the thin and thick lines, where the thick lines are the same  
678 lines as in Fig. 5a. Green symbols are additional data used by Cenedese and Adduce (2010)  
679 to test their parameterization. The solid gray and open black symbols are the same data as  
680 in Fig. 5a for the rough and smooth bottom, respectively. The different symbols represent  
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685 are for  $Re = 14$  and  $Re = 40$  which are the limits between different regimes for the smooth  
686 experiments of Cenedese and Adduce (2008). . . . . 40

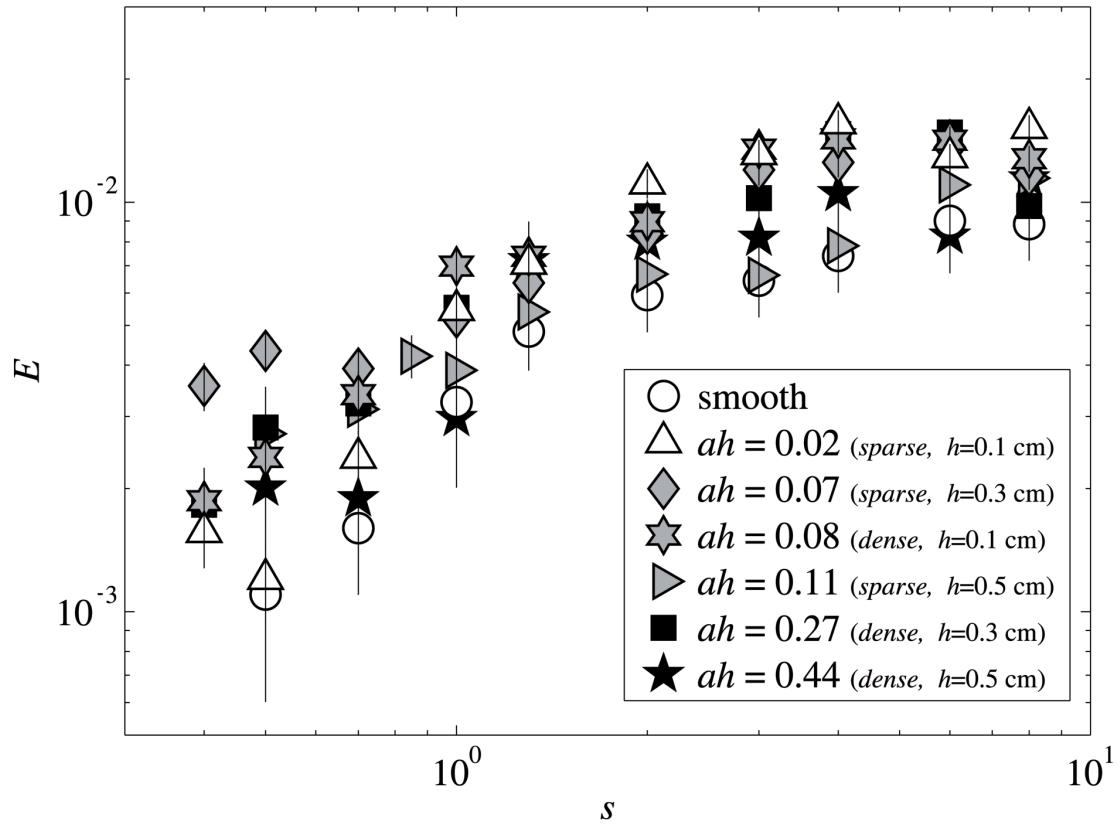
687 **Fig. 7.** Entrainment parameter dependence on  $Fr^2 Re$ . Symbols as in Fig. 3. Error bars are calcu-  
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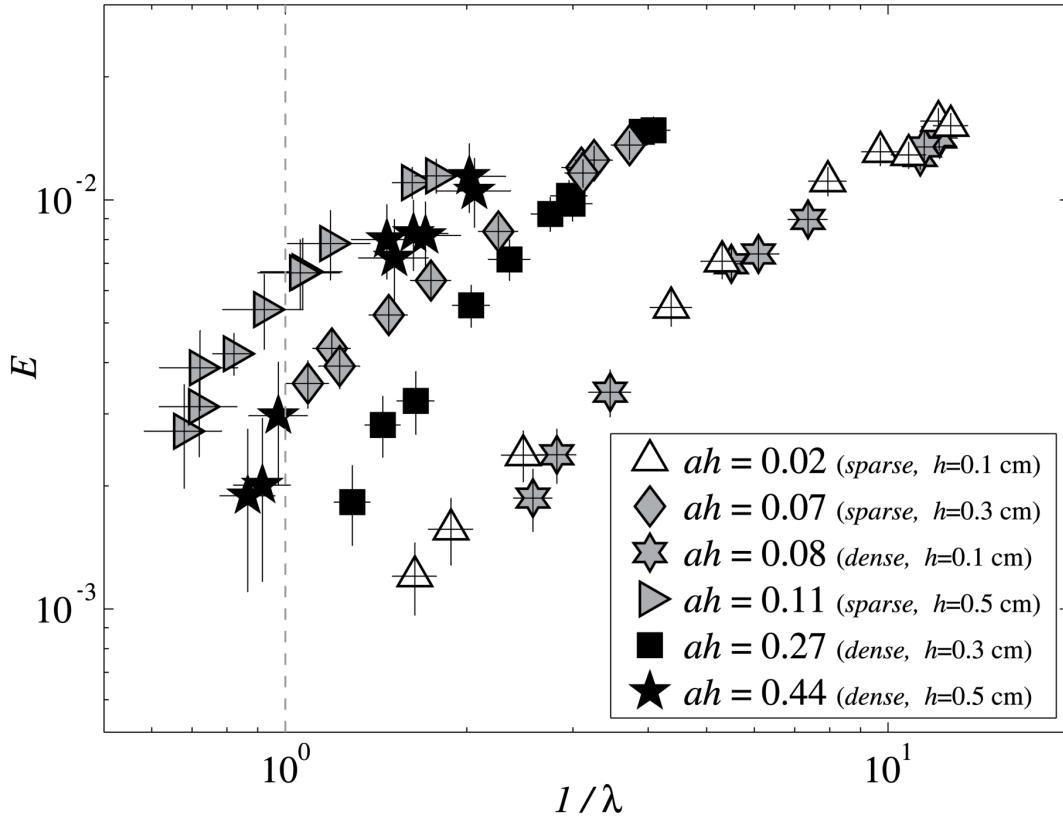
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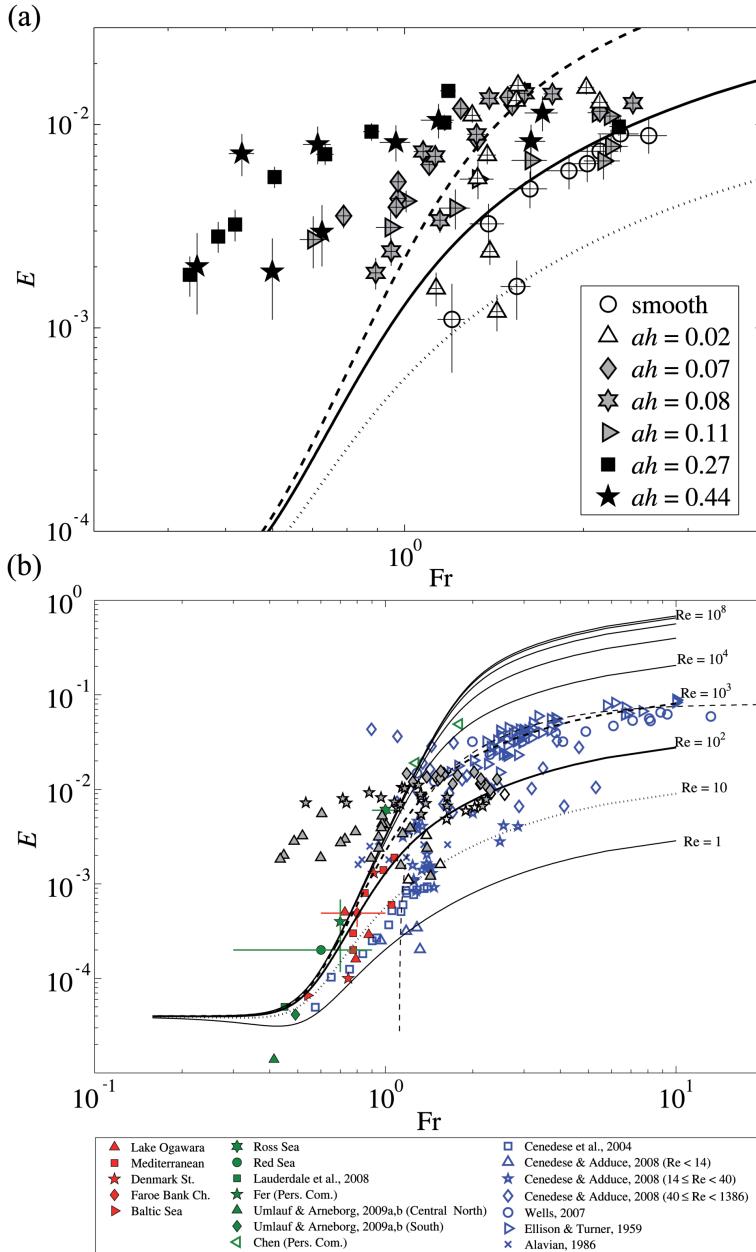
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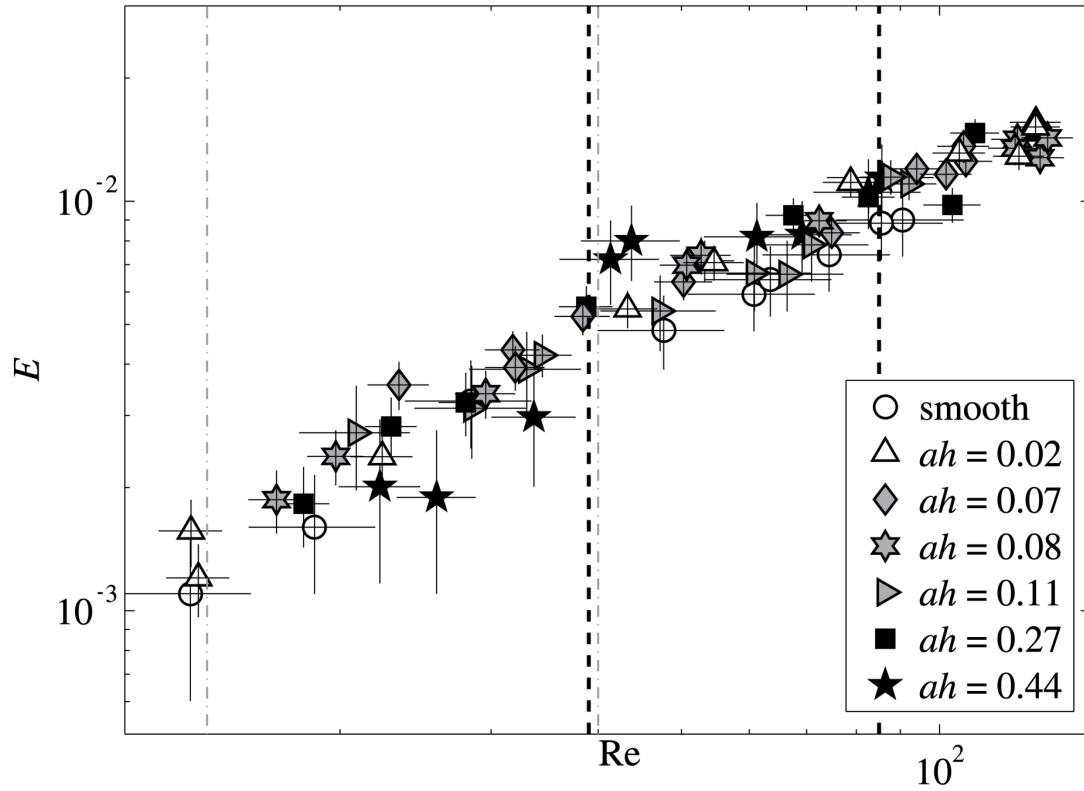
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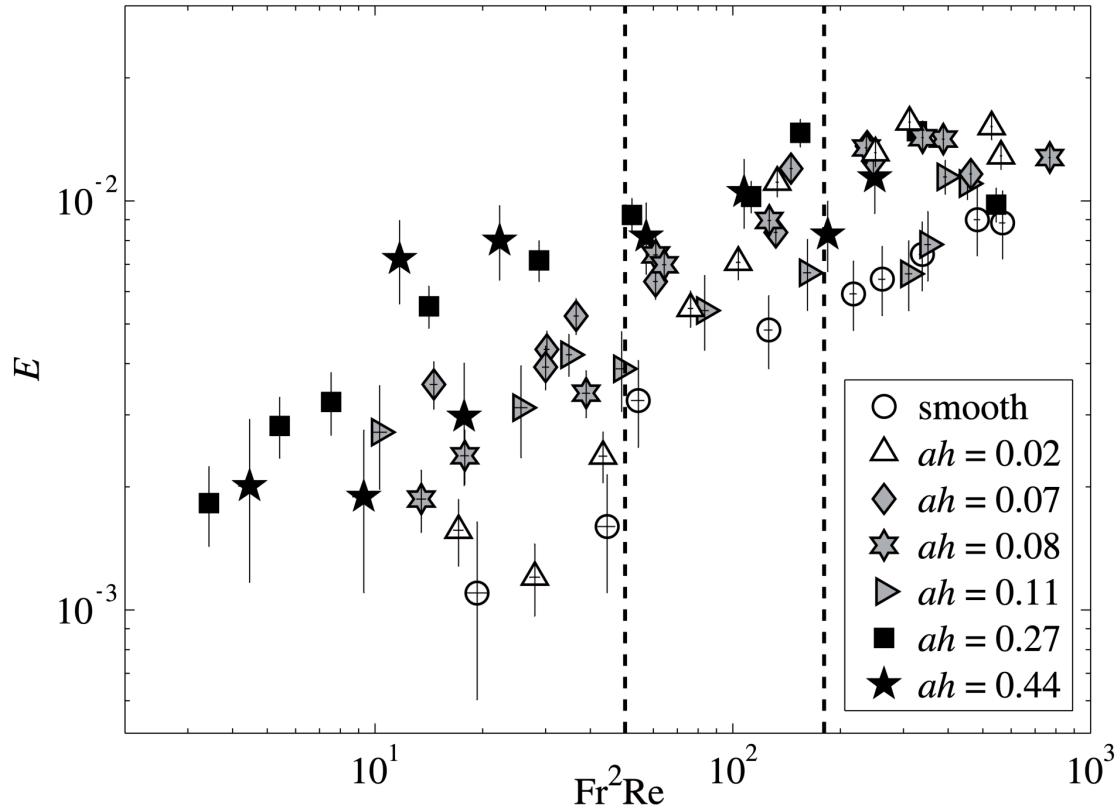
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